

# ASGARD1

# Automotive radar verification

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VOLVO

# Background

- Background in radar, signal and image processing, FPGA, AI, neural networks and network security
- Got PhD in 2013 in communication engineering and cognitive radio
- Founded Uniquesec AB in 2013 for radar signal processing
- First contract for radar-based level measurement in 2014
- Fahimeh joined in March 2015
- Two patent applications filed in 2015 and 5 in 2016
- Investment of 1.9M SEK secured in 2015 and 1M SEK in 2017
- Three patents granted for automotive radar verification in 2017



# Uniquesec Products

- UR2: Advanced radar system
- ASGARD1: Automatic Signature Generation for Automotive Radars
- RDP1: Radar Development Platform
- ARCS: Automatic Radar Characterisation and Calibration System





# Difficult verification

- Complex systems are hard to verify
- Long expeditions is needed
- Ground truth is missing
- Rare and important cases are not easily observed
- Too many cases and scenarios exists for verification
- Different sensors and hardware



With a fleet of 100 autonomous vehicles being test-driven 24 hours a day, 365 days a year at an average speed of 25 miles per hour, this would take about 12.5 years.



# Current verification vs. our solution

## • Cons

- Test in chamber for characterization
- Test by driving expedition
  - Missing ground truth
  - Uncontrolled environment
  - Cannot be reproduced
  - Expensive and time consuming
  - Does not cover rare situations
  - Hard to differentiate sensor vs. function performance

## • Pros

- Improved verification quality
- Capturing reality in the lab
- Fully controlled and randomized scenario generation
- HIL setup for real-time sensor/function characterization
- Cheap and accessible
- Cover dangerous scenarios
- **FULL CONTROL OVER GROUND TRUTH**

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